## CLUSTERING

فعبل (۱: توسَّ سنای

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### ا کارتری مدن نظارت Basic Concepts

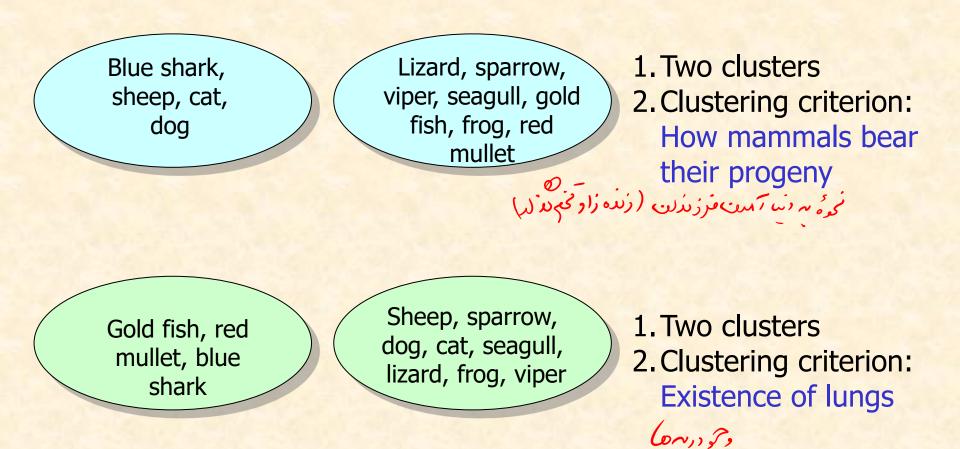
In clustering or unsupervised learning no training data, with class labeling, are available. The goal becomes: Group the data into a number of sensible clusters (groups). This unravels similarities and differences among the available data.

> Applications:

- Engineering
- Bioinformatics
- Social Sciences
- Medicine
- Data and Web Mining

> To perform clustering of a data set, a clustering criterion must first be adopted. Different clustering criteria lead, in general, to different clusters.

#### > A simple example



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go) dfish red-mullet blue shark Frog

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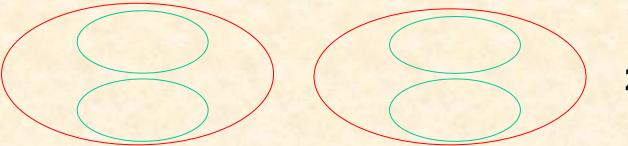
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#### Clustering task stages

- Feature Selection: Information rich features-Parsimony
- Proximity Measure: This quantifies the term similar or dissimilar.
- Clustering Criterion: This consists of a cost function or some type of rules.
- Clustering Algorithm: This consists of the set of steps followed to reveal the structure, based on the similarity measure and the adopted criterion.
- Validation of the results.
- Interpretation of the results.

Depending on the similarity measure, the clustering criterion and the clustering algorithm different clusters may result. Subjectivity is a reality to live with from now on.

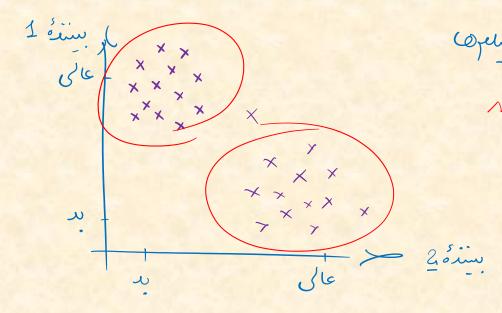
> A simple example: How many clusters??



2 or 4 ??

### Basic application areas for clustering

- Data reduction. All data vectors within a cluster are substituted (represented) by the corresponding cluster representative.
- Hypothesis generation.
- > Hypothesis testing.
- Prediction based on groups.



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Clustering Definitions

Hard Clustering: Each point belongs to a single cluster

• Let 
$$X = \{\underline{x}_1, \underline{x}_2, \dots, \underline{x}_N\}$$

An *m*-clustering *R* of *X*, is defined as the partition of *X* into *m* sets (clusters), *C*<sub>1</sub>, *C*<sub>2</sub>, ..., *C<sub>m</sub>*, so that

$$- C_i \neq \emptyset, i = 1, 2, ..., m$$

$$- \qquad \bigcup_{i=1}^m C_i = X$$

 $C_{1}, C_{1} \qquad m=3$   $(x, y) \qquad (x, y)$ 

 $-C_i \cap C_j = \emptyset, \ i \neq j, \ i, j = 1, 2, ..., m$ 

In addition, data in  $C_i$  are more similar to each other and less similar to the data in the rest of the clusters. Quantifying the terms similar-dissimilar depends on the types of clusters that are expected to underlie the structure of *X*. Fuzzy clustering: Each point belongs to all clusters up to some degree.

A fuzzy clustering of *X* into *m* clusters is characterized by *m* functions

• 
$$u_j : \underline{x} \to [0,1], \quad j = 1, 2, ..., m$$
  
•  $\sum_{j=1}^m u_j(\underline{x}_i) = 1, \quad i = 1, 2, ..., N$   
•  $0 < \sum_{i=1}^N u_j(\underline{x}_i) < N, \quad j = 1, 2, ..., m$ 

These are known as membership functions. Thus, each  $\underline{x}_i$  belongs to any cluster "up to some degree", depending on the value of

$$u_{j}(\underline{x}_{i}), \ j = 1, 2, ..., m$$

 $u_j(\underline{x}_i)$  close to  $1 \Rightarrow$  high grade of membership  $\underline{x}_i$  to cluster j.  $u_j(\underline{x}_i)$  close to  $0 \Rightarrow$ low grade of membership.

# **TYPES OF FEATURES**

With respect to their <u>domain</u>

- > Continuous (the domain is a continuous subset of  $\Re$ ).
- Discrete (the domain is a finite discrete set).
  - *Binary* or *dichotomous* (the domain consists of two possible values).
- With respect to the <u>relative significance of the values they</u> <u>take</u>
  - Nominal (the values code states, e.g., the sex of an individual).
  - Ordinal (the values are meaningfully ordered, e.g., the rating of the services of a hotel (poor, good, very good, excellent)).
  - Interval-scaled (the difference of two values is meaningful but their ratio is meaningless, e.g., temperature).
  - Ratio-scaled (the ratio of two values is meaningful, e.g., weight).

## **PROXIMITY MEASURES**

Between vectors

Dissimilarity measure (between vectors of X) is a function

 $d: X \times X \longrightarrow \Re$ 

with the following properties

•  $\exists d_0 \in \Re: -\infty < d_0 \le d(\underline{x}, \underline{y}) < +\infty, \ \forall \underline{x}, \underline{y} \in X$ 

• 
$$d(\underline{x},\underline{x}) = d_0, \ \forall \underline{x} \in X$$

•  $d(\underline{x}, \underline{y}) = d(\underline{y}, \underline{x}), \ \forall \underline{x}, \underline{y} \in X$ 

### If in addition

- $d(\underline{x}, \underline{y}) = d_0$  if and only if  $\underline{x} = \underline{y}$
- $d(\underline{x},\underline{z}) \le d(\underline{x},\underline{y}) + d(\underline{y},\underline{z}), \ \forall \underline{x},\underline{y},\underline{z} \in X$

(triangular inequality)

d is called a metric dissimilarity measure.

Similarity measure (between vectors of X) is a function

 $s: X \times X \longrightarrow \Re$ 

with the following properties

- $\exists s_0 \in \mathfrak{R}: -\infty < s(\underline{x}, \underline{y}) \le s_0 < +\infty, \ \forall \underline{x}, \underline{y} \in X$
- $s(\underline{x}, \underline{x}) = s_0, \ \forall \underline{x} \in X$
- $s(\underline{x}, \underline{y}) = s(\underline{y}, \underline{x}), \ \forall \underline{x}, \underline{y} \in X$

#### If in addition

•  $s(\underline{x}, \underline{y}) = s_0$  if and only if  $\underline{x} = \underline{y}$ 

•  $s(\underline{x}, \underline{y})s(\underline{y}, \underline{z}) \leq [s(\underline{x}, \underline{y}) + s(\underline{y}, \underline{z})]s(\underline{x}, \underline{z}), \ \forall \underline{x}, \underline{y}, \underline{z} \in X$ 

*s* is called a metric similarity measure.

★ <u>Between sets</u> Let  $D_i \subset X$ , i=1,...,k and  $U=\{D_1,...,D_k\}$ A proximity measure ℘ on U is a function ℘: U×U → ℜ

A dissimilarity measure has to satisfy the relations of dissimilarity measure between vectors, where  $D_i$ 's are used in place of <u>x</u>, <u>y</u> (similarly for similarity measures).

# **PROXIMITY MEASURES BETWEEN VECTORS**

Real-valued vectors

- Dissimilarity measures (DMs)
  - Weighted  $l_p$  metric DMs

$$d_p(\underline{x},\underline{y}) = \left(\sum_{i=1}^l w_i \mid x_i - y_i \mid^p\right)^{1/p}$$

Interesting instances are obtained for -p=1 (weighted Manhattan norm) -p=2 (weighted Euclidean norm)  $-p=\infty (d_{\infty}(\underline{x}, \underline{y})=\max_{1 \le i \le l} w_i |x_i - y_i|)$   $\underbrace{x = [4, 3, 2]^T}_{\substack{y = [4, 3, 2]^T}} \longrightarrow d_1(\underbrace{x}, \underbrace{y}) = \widehat{y}$   $d_{\infty}(\underbrace{x}, \underbrace{y}) = \widehat{y}$   $d_{\infty}(\underbrace{x}, \underbrace{y}) = \widehat{y}$  • Other measures

$$- d_G(\underline{x}, \underline{y}) = -\log_{10}\left(1 - \frac{1}{l}\sum_{j=1}^l \frac{|x_j - y_j|}{\underline{b}_j - \underline{a}_j}\right)$$

where  $b_j$  and  $a_j$  are the maximum and the minimum values of the *j*-th feature, among the vectors of *X* (dependence on the current data set)

$$d_{\mathcal{Q}}(\underline{x},\underline{y}) = \sqrt{\frac{1}{l} \sum_{j=1}^{l} \left(\frac{x_j - y_j}{x_j + y_j}\right)^2}$$

 $\frac{b}{a} = [10, 12, 13]^{T}$   $a = [0, 0.5, 1]^{T}$   $d_{g} = 0.590$ 



• Inner product

$$S_{inner}(\underline{x},\underline{y}) = \underline{x}^T \underline{y} = \sum_{i=1}^l x_i y_i$$

• Tanimoto measure

• 
$$s_T(\underline{x}, \underline{y}) = \frac{\underline{x}^T \underline{y}}{\|\underline{x}\|^2 + \|\underline{y}\|^2 - \underline{x}^T \underline{y}}$$
• 
$$s_T(\underline{x}, \underline{y}) = 1 - \frac{d_2(\underline{x}, \underline{y})}{\|\underline{x}\| + \|\underline{y}\|}$$

#### Discrete-valued vectors

- ≻ Let  $F = \{0, 1, ..., k-1\}$  be a set of symbols and  $X = \{\underline{x}_1, ..., \underline{x}_N\} \subset F^l$
- ➤ Let  $A(\underline{x},\underline{y}) = [a_{ij}]$ , *i*, *j*=0,1,...,*k*-1, where  $a_{ij}$  is the number of places where  $\underline{x}$  has the *i*-th symbol and  $\underline{y}$  has the *j*-th symbol.

$$\sum_{i=0}^{k-1} \sum_{j=0}^{k-1} a_{ij} =$$

#### NOTE:

Several proximity measures can be expressed as combinations of the elements of  $A(\underline{x},\underline{y})$ .

Dissimilarity measures:

• The Hamming distance (number of places where <u>x</u> and <u>y</u> differ)

$$d_H(\underline{x},\underline{y}) = \sum_{i=0}^{n-1} \sum_{\substack{j=0\\j\neq i}}^{n-1} a_{ij}$$

• The  $l_1$  distance

$$d_1(\underline{x},\underline{y}) = \sum_{i=1}^{i} |x_i - y_i|$$

Similarity measures:

• Tanimoto measure : 
$$s_T(\underline{x}, \underline{y}) = \frac{\sum_{i=1}^{k-1} a_{ii}}{n_x + n_y - \sum_{i=1}^{k-1} \sum_{j=1}^{k-1} a_{ij}}$$

where 
$$n_x = \sum_{i=1}^{\infty} \sum_{j=0}^{\infty} a_{ij}, \quad n_y = \sum_{i=0}^{\infty} \sum_{j=1}^{\infty} a_{ij},$$

• Measures that exclude  $a_{00}$ :

$$\sum_{i=1}^{k-1} a_{ii} / l \qquad \sum_{i=1}^{k-1} a_{ii} / (l - a_{00})$$

<u>k-1</u>

• Measures that include  $a_{00}$ :

$$\sum_{i=0}^{k-1} a_{ii} / l$$

### Mixed-valued vectors

Some of the coordinates of the vectors  $\underline{x}$  are real and the rest are discrete.

Methods for measuring the proximity between two such  $\underline{x}_i$  and  $\underline{x}_i$ :

- Adopt a proximity measure (PM) suitable for real-valued vectors.
- Convert the real-valued features to discrete ones and employ a discrete PM.

The more general case of mixed-valued vectors:

Here nominal, ordinal, interval-scaled, ratio-scaled features are treated separately. The similarity function between  $\underline{x}_i$  and  $\underline{x}_i$  is:

$$S(\underline{x}_i, \underline{x}_j) = \sum_{q=1}^l S_q(\underline{x}_i, \underline{x}_j) / \sum_{q=1}^l W_q$$

In the above definition:

- w<sub>q</sub>=0, if at least one of the *q*-th coordinates of <u>x</u><sub>i</sub> and <u>x</u><sub>j</sub> are undefined or both the *q*-th coordinates are equal to 0. Otherwise w<sub>q</sub>=1.
- If the *q*-th coordinates are binary,  $s_q(\underline{x}_i, \underline{x}_j)=1$  if  $x_{iq}=x_{jq}=1$  and 0 otherwise.
- If the *q*-th coordinates are nominal or ordinal,  $s_q(\underline{x}_i, \underline{x}_j)=1$  if  $x_{iq}=x_{jq}$ and 0 otherwise.
- If the *q*-th coordinates are interval or ratio scaled-valued

$$S_q(\underline{x}_i, \underline{x}_j) = 1 - |x_{iq} - x_{jq}| / r_q,$$

where  $r_q$  is the interval where the q-th coordinates of the vectors of the data set X lie.

### Fuzzy measures

Let  $\underline{x}, \underline{y} \in [0,1]^l$ . Here the value of the *i*-th coordinate,  $x_{i}$ , of  $\underline{x}$ , is **not** the outcome of a measuring device.

- > The closer the coordinate  $x_i$  is to 1 (0), the more likely the vector <u>x</u> possesses (does not possess) the *i*-th characteristic.
- As x<sub>i</sub> approaches 0.5, the certainty about the possession or not of the *i*-th feature from <u>x</u> decreases.

A possible similarity measure that can quantify the above is:  $s(x_i, y_i) = \max(\min(1 - x_i, 1 - y_i), \min(x_i, y_i))$ 

Then

$$s_F^q(\underline{x},\underline{y}) = \left(\sum_{i=1}^l s(x_i,y_i)^q\right)^{1/q}$$

#### Missing data

For some vectors of the data set *X*, some features values are unknown

#### Ways to face the problem:

- Discard all vectors with missing values (not recommended for small data sets)
- Find the mean value  $m_i$  of the available *i*-th feature values over that data set and substitute the missing *i*-th feature values with  $m_i$ .
- Define b<sub>i</sub>=0, if both the *i*-th features x<sub>i</sub>, y<sub>i</sub> are available and 1 otherwise. Then

$$\wp(\underline{x},\underline{y}) = \frac{l}{l - \sum_{i=1}^{l} b_i} \sum_{all \ i: \ b_i = 0} \phi(x_i, y_i)$$

where  $\phi(x_i, y_i)$  denotes the PM between two scalars  $x_i, y_i$ .

> Find the average proximities  $\phi_{avg}(i)$  between all feature vectors in X along all components. Then

$$\wp(\underline{x},\underline{y}) = \sum_{i=1}^{l} \psi(x_i, y_i)$$

where  $\psi(x_i, y_i) = \phi(x_i, y_i)$ , if both  $x_i$  and  $y_i$  are available and  $\phi_{avg}(i)$  23 otherwise.

# PROXIMITY FUNCTIONS BETWEEN A VECTOR AND A SET

 $\bigstar \text{ Let } X = \{ \underline{x}_1, \underline{x}_2, \dots, \underline{x}_N \} \text{ and } C \subset X, \underline{x} \in X \}$ 

All points of C contribute to the definition of ℘(x, C)
 Max proximity function

 $\mathscr{D}_{\max}^{ps}(\underline{x},C) = \max_{y \in C} \mathscr{D}(\underline{x},\underline{y})$ 

Min proximity function

 $\mathscr{D}_{\min}^{ps}(\underline{x}, C) = \min_{y \in C} \mathscr{D}(\underline{x}, \underline{y})$ 

Average proximity function

 $\mathscr{D}_{avg}^{ps}(\underline{x},C) = \frac{1}{n_C} \sum_{\underline{y} \in C} \mathscr{D}(\underline{x},\underline{y}) \qquad (n_C \text{ is the cardinality of } C)$ 

A representative(s) of C, r<sub>c</sub>, contributes to the definition of  $\wp(x,C)$ In this case:  $\wp(\underline{x},C) = \wp(\underline{x},\underline{r}_{C})$ Typical representatives are: > The mean vector:  $\underline{m}_p = \left(\frac{1}{n_c}\right) \sum_{c} \underline{y}$ where  $n_C$  is the cardinality of C > The mean center: d: a dissimilarity measure  $\underline{m}_{C} \in C: \sum_{y \in C} d(\underline{m}_{C}, \underline{y}) \leq \sum_{y \in C} d(\underline{z}, \underline{y}), \ \forall \underline{z} \in C$ > The median center:  $\underline{m}_{med} \in C: med(d(\underline{m}_{med}, y) | y \in C) \le med(d(\underline{z}, y) | y \in C), \forall \underline{z} \in C$ **NOTE:** Other representatives (e.g., hyperplanes, hyperspheres) are

useful in certain applications (e.g., object identification using clustering techniques).

## **PROXIMITY FUNCTIONS BETWEEN SETS**

 $\bigstar \text{ Let } X = \{\underline{x}_1, \dots, \underline{x}_N\}, D_i, D_j \subset X \text{ and } n_i = |D_i|, n_j = |D_j|$ 

All points of each set contribute to  $\mathcal{P}(D_i, D_i)$ 

Max proximity function (measure but not metric, only if so is a similarity measure)

$$\mathcal{O}_{\max}^{ss}(D_i, D_j) = \max_{\underline{x} \in D_i, \underline{y} \in D_j} \mathcal{O}(\underline{x}, \underline{y})$$

Min proximity function (measure but not metric, only if p is a dissimilarity measure)

$$\mathscr{D}_{\min}^{ss}(D_i, D_j) = \min_{\underline{x} \in D_i, y \in D_j} \mathscr{D}(\underline{x}, \underline{y})$$

Average proximity function (not a measure, even if p is a measure)

$$\mathcal{G}_{avg}^{ss}(D_i, D_j) = \left(\frac{1}{n_i n_j}\right) \sum_{x \in D_i} \sum_{x \in D_j} \mathcal{G}(\underline{x}, \underline{y})$$

◆ Each set D<sub>i</sub> is represented by its representative vector <u>m<sub>i</sub></u>
 > Mean proximity function (it is a measure provided that ℘ is a measure):

$$\mathscr{D}_{mean}^{ss}(D_i, D_j) = \mathscr{D}(\underline{m}_i, \underline{m}_j)$$

$$\succ \qquad \wp_e^{ss}(D_i, D_j) = \sqrt{\frac{n_i n_j}{n_i + n_j}} \wp(\underline{m}_i, \underline{m}_j)$$

**NOTE:** Proximity functions between a vector  $\underline{x}$  and a set *C* may be derived from the above functions if we set  $D_i = \{\underline{x}\}$ .

### > Remarks:

- Different choices of proximity functions between sets may lead to totally different clustering results.
- Different proximity measures between vectors in the same proximity function between sets may lead to totally different clustering results.
- The only way to achieve a proper clustering is
  - by trial and error and,
  - taking into account the opinion of an expert in the field of application.